

Properties of Laplace Operators for Tetrahedral Meshes

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 Many applications in geometry processing: deformation, parameterization, heat diffusion, uniformization.



All these examples have direct analogies for tetrahedral meshes.

• All Laplacians we consider here are given by weights w_{ij} .

$$(\mathbf{Lf})_i = \sum_{(i,j)\in\mathcal{M}} w_{ij} (f_j - f_i) \qquad w_{ij} = w_{ji}$$

 Properties by construction: (weak) locality, symmetry, constants are part of the null space.

Additional desirable properties:

negative semi-definite

Dirichlet energy $-\mathbf{f}^{\top}\mathbf{L}\mathbf{f}$ is non-negative for any function \mathbf{f} .

positive coefficients w_{ij} Maximum principle.

linear precision

 $(\mathbf{Lf})_i = 0$ for inner vertices i and linear functions \mathbf{f} .

- Discrete Laplacians are widely studied for triangle meshes.
- Arguably the most common choice:

cotan Laplacian

(negative semi-definite, symmetric, linear precision, local)

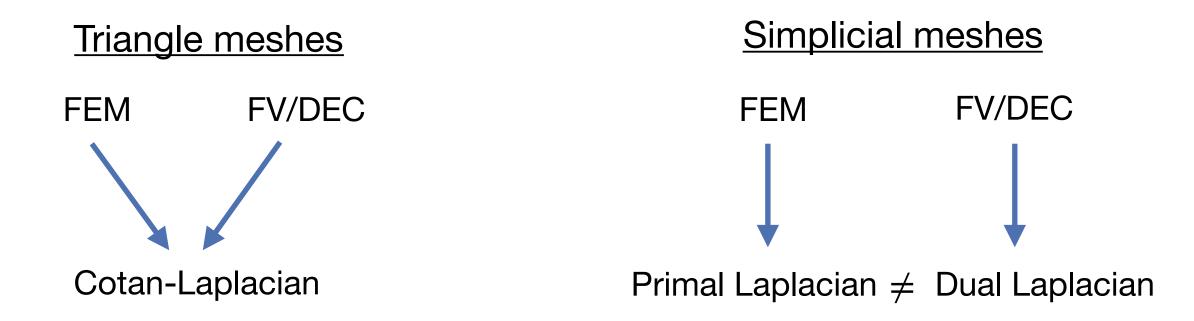
• If maximum principle is needed for non-Delaunay meshes:

intrinsic cotan Laplacian

(negative semi-definite, symmetric, linear precision, positivity)

• Is there a similar default option for simplicial meshes?

Short answer: No



• Is there a similar default option for simplicial meshes?

Detailed answer:

Eurographics Symposium on Geometry Processing 2020 Q. Huang and A. Jacobson (Guest Editors)

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Properties of Laplace Operators for Tetrahedral Meshes

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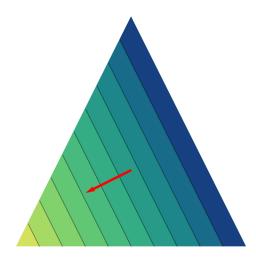
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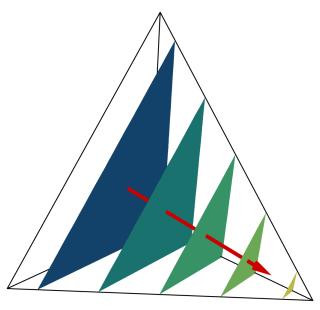
Abstract

Discrete Laplacians for triangle meshes are a fundamental tool in geometry processing. The so-called cotan Laplacian is widely used since it preserves several important properties of its smooth counterpart. It can be derived from different principles: either considering the piecewise linear nature of the primal elements or associating values to the dual vertices. Both approaches lead to the same operator in the two-dimensional setting. In contrast, for tetrahedral meshes, only the primal construction is reminiscent of the cotan weights, involving dihedral angles. We provide explicit formulas for the lesser-known dual construction. In both cases, the weights can be computed by adding the contributions of individual tetrahedra to an edge. The resulting two different discrete Laplacians for tetrahedral meshes only retain some of the properties of their two-dimensional counterpart. In particular, while both constructions have linear precision, only the primal construction is positive semi-definite and only the

- Each vertex v_i has a unique function b_i that is
 - linear on the elements (triangles/tetrahedra).
 - fulfills $b_i(v_j) = \delta_{ij}$.
- Represent function in this basis

$$f = \sum_{i} f_i b_i$$



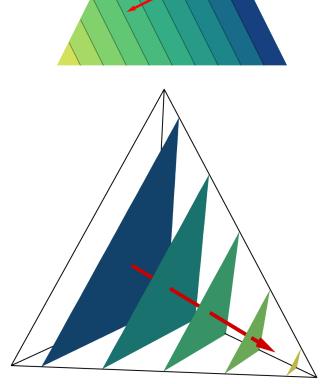


• Gradients of b_i are constant on elements.

Gradient of piecewise linear function by linearity.

$$\nabla f = \nabla \sum_{i} f_i b_i = \sum_{i} f_i \nabla b_i$$

A matrix G maps vertex values to gradients.

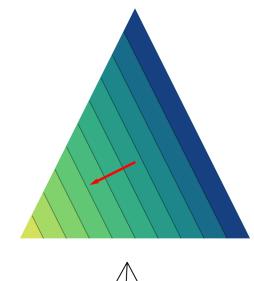


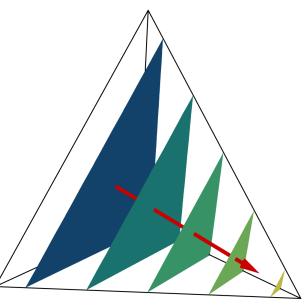
• Divergence is the adjoint of the gradient

$$\mathbf{D} = -\mathbf{G}^{ op} \mathbf{A}$$

- A is a diagonal matrix containing areas/volumes.
- The Laplacian can be defined as divergence of the gradient:

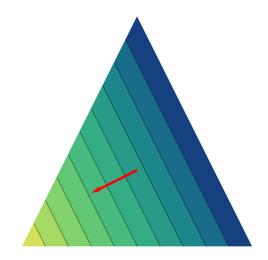
$$\mathbf{L} = -\mathbf{G}^{ op} \mathbf{A} \mathbf{G}$$

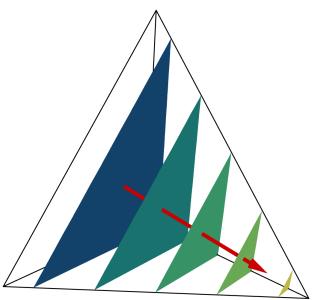




$$\mathbf{L} = -\mathbf{G}^{\mathsf{T}} \mathbf{A} \mathbf{G}$$

- Negative semi-definite by construction.
- Linear functions are exactly reproduced.
- ⇒ linear precision: the Laplacian of linear functions vanishes (at interior vertices).



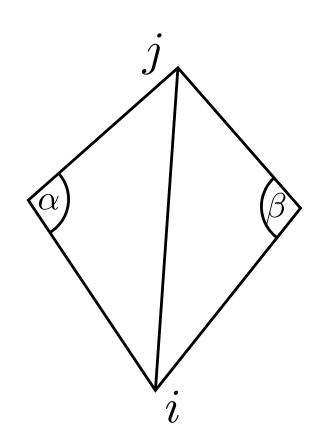


$$\mathbf{L} = -\mathbf{G}^{\top} \mathbf{A} \mathbf{G}$$

• Yields cotan Laplacian for triangle meshes.

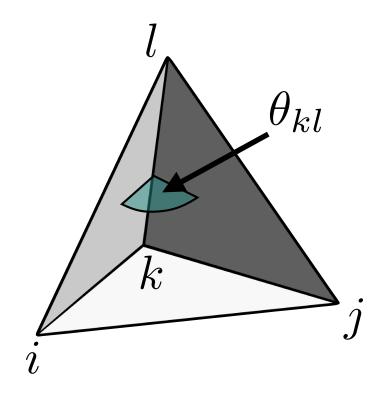
$$w_{ij} = \frac{1}{2}\cot\alpha + \frac{1}{2}\cot\beta$$

Construction per triangle.



Analogous formula for tetrahedral meshes

$$w_{ij} = \frac{1}{6} \sum_{(ijkl) \in \mathcal{M}} \|\mathbf{v}_k - \mathbf{v}_l\| \cot \theta_{kl}$$

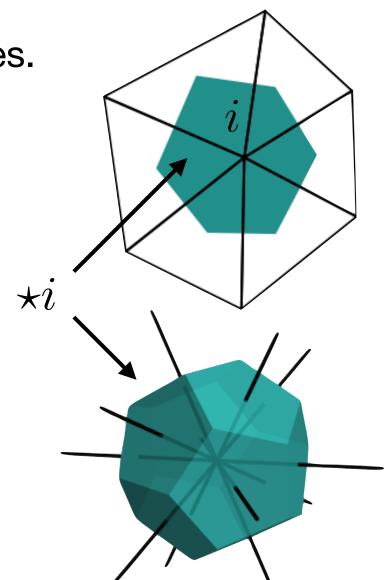


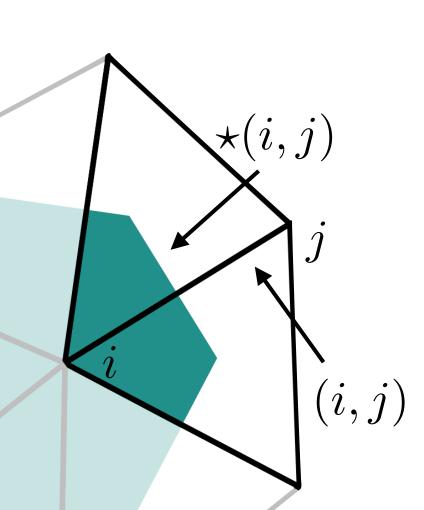
Construction by summing up per element: strong locality.

Associate constant values to volumes at vertices.

• Use circumcentric dual volumes $\star i$.

$$\int_{\star i} \Delta f \ dV = \int_{\star i} \nabla (\nabla f) \ dV = \int_{\partial \star i} (\nabla f) \cdot \mathbf{n} \ dS$$

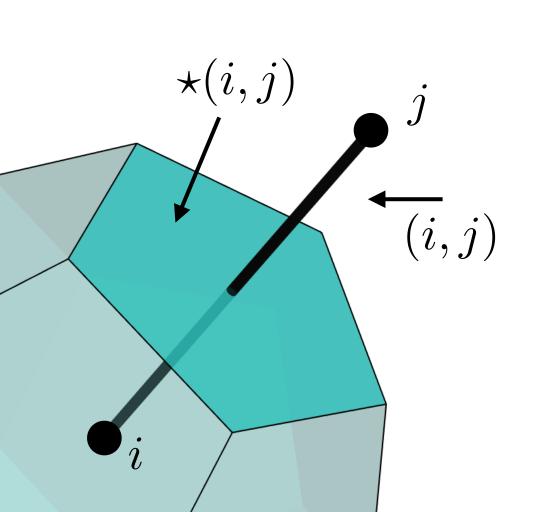




$$\int_{\star i} \Delta f \ dV = \int_{\partial \star i} (\nabla f) \cdot \mathbf{n} \ dS$$

$$\sum_{(ij)\in\mathcal{M}} \frac{(f_j - f_i)}{\operatorname{Vol}(i,j)} \operatorname{Vol}(\star(i,j))$$

$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

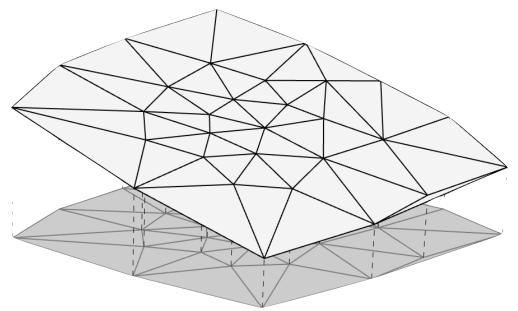


$$\int_{\star i} \Delta f \ dV = \int_{\partial \star i} (\nabla f) \cdot \mathbf{n} \ dS$$

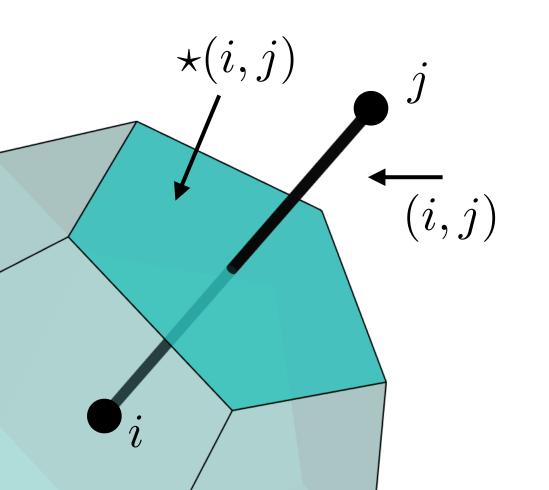
$$\sum_{(ij)\in\mathcal{M}} \frac{(f_j - f_i)}{\operatorname{Vol}(i,j)} \operatorname{Vol}(\star(i,j))$$

$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

- The set (1, x, y, z) spans the space of linear functions.
- Constants are part of the kernel by default.
- Linear precision: $(\mathbf{L}\mathbf{X})_i = 0$ for the vertex positions $\mathbf{X} \in \mathbb{R}^{n \times 3}$.



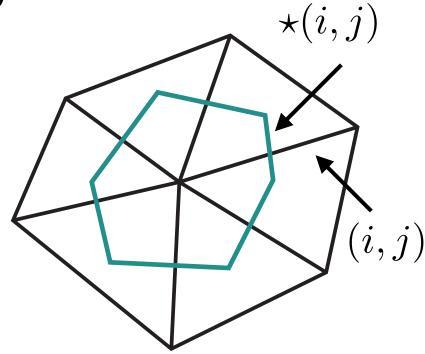
• Linear precision: $(\mathbf{L}\mathbf{X})_i = 0$ for the vertex positions $\mathbf{X} \in \mathbb{R}^{n \times 3}$.



$$\sum_{(ij)\in\mathcal{M}} \frac{(\mathbf{v}_j - \mathbf{v}_i)}{\|\mathbf{v}_j - \mathbf{v}_i\|} \operatorname{Vol}(\star(i,j)) = 0$$

Vector area integrated over a closed surface vanishes.

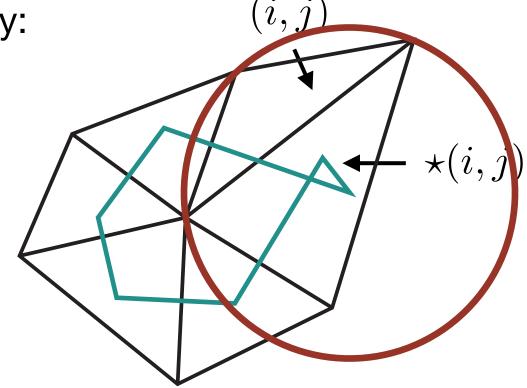
Positivity:



$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

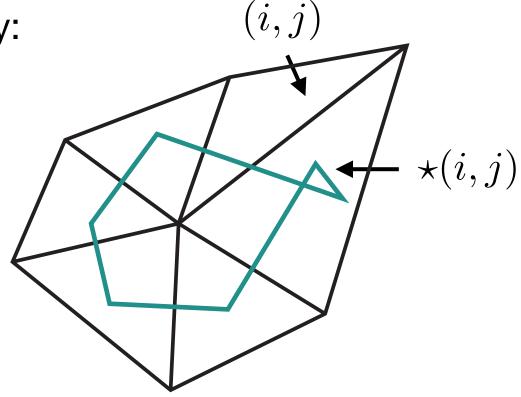
• The vector $\frac{\mathbf{v}_j - \mathbf{v}_i}{\|\mathbf{v}_i - \mathbf{v}_i\|}$ is the *outward* directed boundary normal.





$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

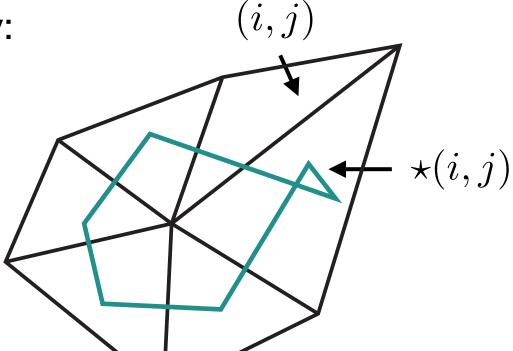
• Positivity:



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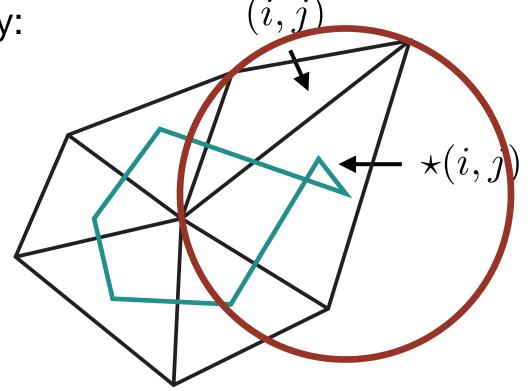
$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

negative dual volume

$$rac{\mathbf{v}_j - \mathbf{v}_i}{\|\mathbf{v}_j - \mathbf{v}_i\|}$$

• The vector $\frac{\mathbf{v}_j - \mathbf{v}_i}{\|\mathbf{v}_i - \mathbf{v}_i\|}$ is the *inward* directed boundary normal.





$$w_{ij} = \frac{\operatorname{Vol}(\star(i,j))}{\operatorname{Vol}(i,j)}$$

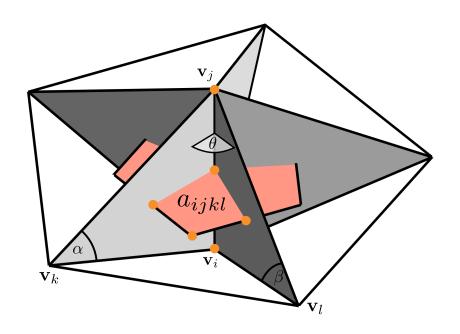
• Delaunay meshes have embedded circumcentric duals => $w_{ij} \ge 0$

Discrete Laplacian: Strong Locality

Element wise construction:

$$w_{ij} = \frac{\|\mathbf{v}_i - \mathbf{v}_j\|}{8} \sum_{ijkl} \cot \theta \left(2 \frac{\cot \alpha \cot \beta}{\cos \theta} - \cot^2 \alpha - \cot^2 \beta \right)$$

- Applies to non-Delaunay meshes.
- Easy boundary treatment.



Discrete Laplacian: Properties

• Properties by construction (finite elements/finite volumes):

symmetry, strong locality, linear precision

• Properties by construction (finite elements):

negative semi-definite

• Properties by construction (finite volumes, Delaunay mesh):

positive coefficients (mesh interior)

Discrete Laplacian: Properties 2d

• For triangle meshes:

finite element Laplace = finite volume Laplace = cotan Laplace

Delaunay meshes:

negative semi-definite and positive coefficients (interior)

non-Delaunay meshes:

negative semi-definite

Discrete Laplacian: Properties 3d

For tetrahedral meshes:

finite element Laplace \neq finite volume Laplace

Discrete Laplacian: Properties 3d

Finite volume Laplace:

Delaunay mesh:

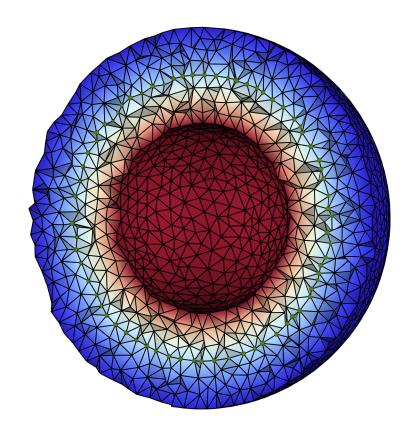
positive weights (away from the boundary)

non-Delaunay mesh:

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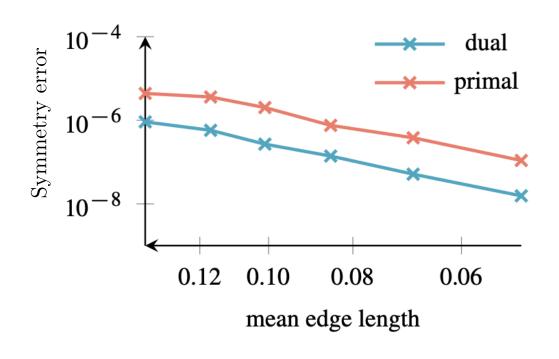
Numerical Experiments

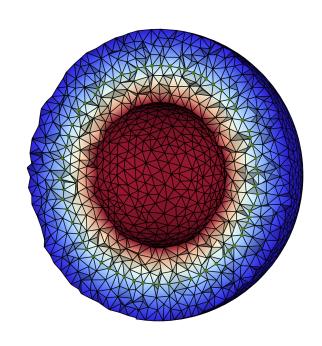
• Minimizing Dirichlet energy: Delaunay mesh



Numerical Experiments

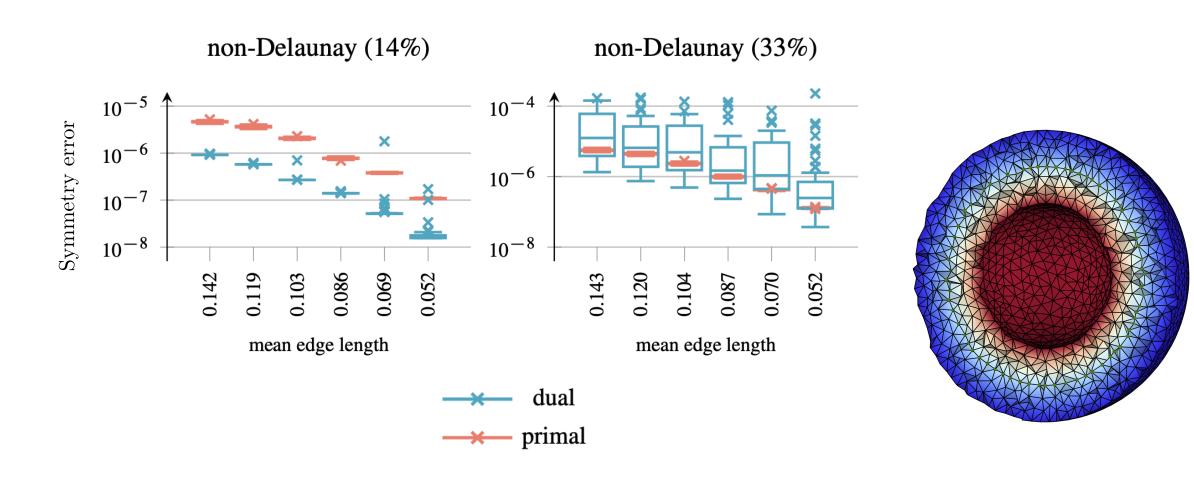
Minimizing Dirichlet energy: Delaunay mesh





Numerical Experiments

Minimizing Dirichlet energy: non-Delaunay mesh



Conclusion

- The choice of Laplacian for simplicial meshes depends on:
 - mesh type
 - problem type
 - numerical method

Thank you.