252-0538-00L, Spring 2025

Shape Modeling and Geometry Processing

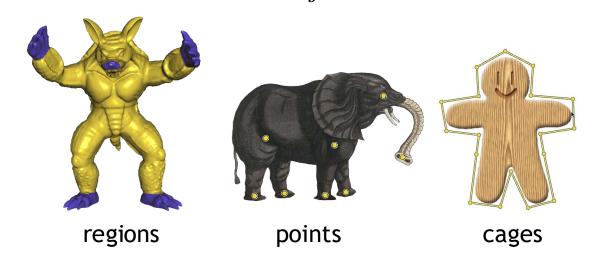




Space deformation with various handle types

So far we saw:
$$\mathbf{f}: \mathbb{R}^3 \to \mathbb{R}^3; \ \mathbf{x}' = \mathbf{f}(\mathbf{x}) = \sum_j w_j(\mathbf{x}) \, \mathbf{p}_j'$$

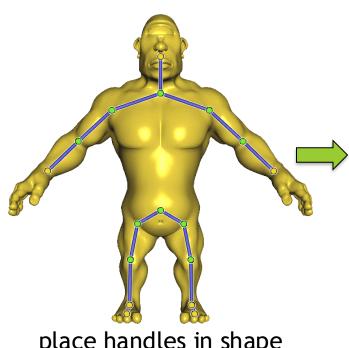
Where \mathbf{p}_j are *positions* of control points of:



Space deformation with various handle types

So far we saw: $\mathbf{f}: \mathbb{R}^3 \to \mathbb{R}^3$; $\mathbf{x}' = \mathbf{f}(\mathbf{x}) = \sum w_j(\mathbf{x}) \, \mathbf{p}'_j$ How to generalize to include skeletons, bone rotations...? skeletons regions points cages

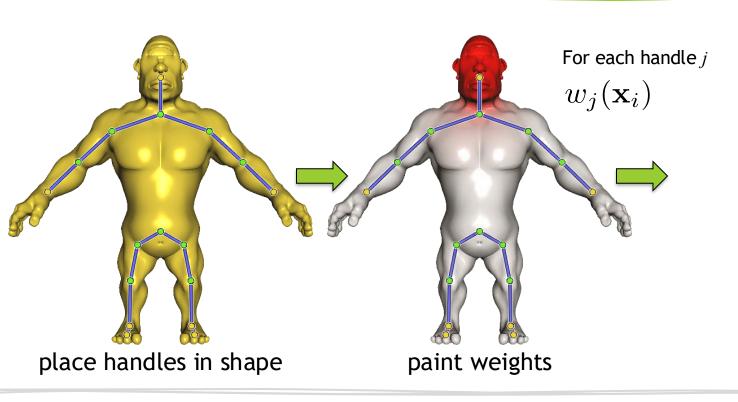




place handles in shape

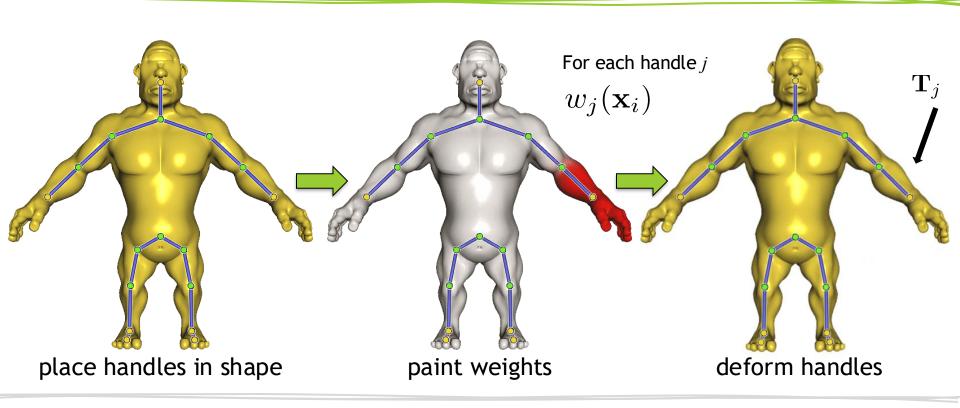








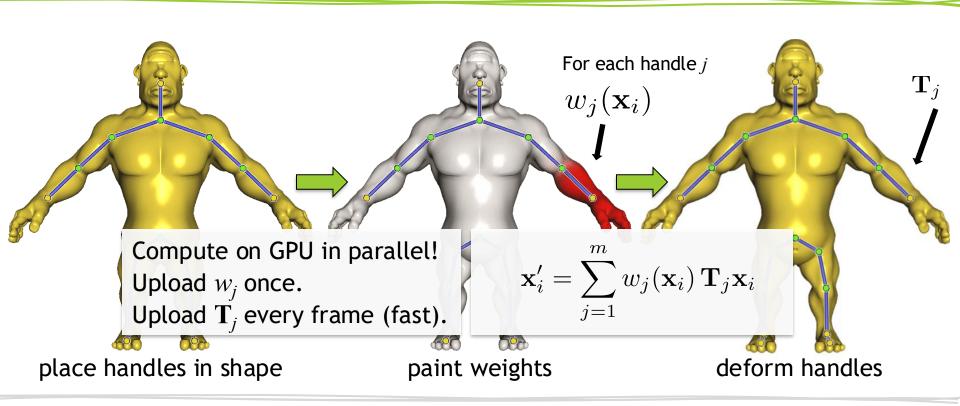








Realtime performance, parallelizable





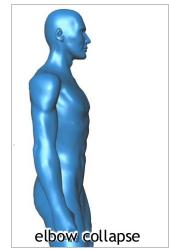


LBS alone is not good enough

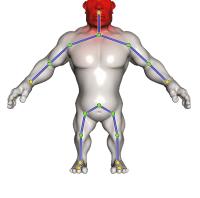
- Manual weight painting
 - Unintuitive and tedious

$$\mathbf{x}_i' = \sum_{j=1}^m w_j(\mathbf{x}_i) \, \mathbf{T}_j \mathbf{x}_i$$

- Artifacts due to linear nature
 - "Elbow collapse"
 - "Candy wrapper"



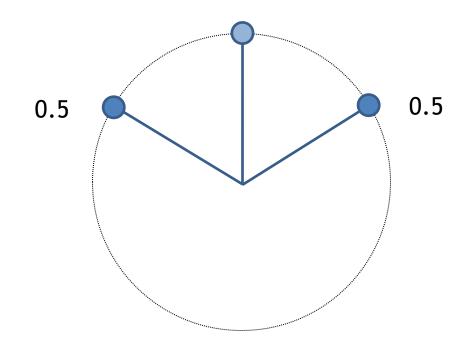








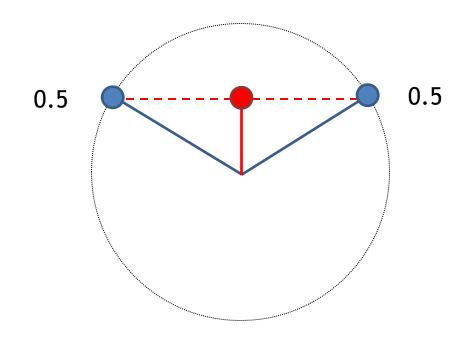
Correct rotation interpolation







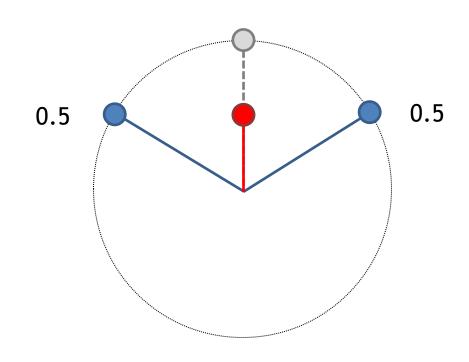
Linear interpolation







Linearization of rotations leads to artifacts







LBS alone is not good enough

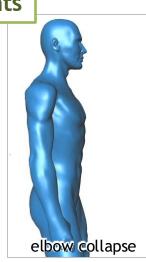
- Manual weight painting
 - Unintuitive and tedious

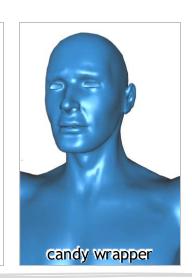
$$\mathbf{x}_i' = \sum_{j=1}^m w_j(\mathbf{x}_i) \, \mathbf{T}_j \mathbf{x}_i$$

Algorithm to compute the weights

- Artifacts due to linear nature
 - "Elbow collapse"
 - "Candy wrapper"

Plug into ARAP as a subspace









Further reading

 Bounded Biharmonic Weights https://igl.ethz.ch/projects/bbw/

 Fast Automatic Skinning Transformations <u>https://igl.ethz.ch/projects/fast/</u>

 Elasticity-Inspired Deformers for Character Articulation <u>https://igl.ethz.ch/projects/eid/</u>





May 14, 2025

Next week: Guest Lecture!

May 21, 10:15:

Prof. Barbara Solenthaler

Multimodal 3D head modeling and simulation for medical applications





Thank You!



