## Shape Modeling and Geometry Processing Assignment 1 - libigl "Hello world"







# **Exercise Sessions**

- Friday from 11:15-12:00
- Exercise presentation + Q&A + live demo
- Course website: <u>http://igl.ethz.ch/teaching/</u> shape-modeling/sm2025/
- Assistants: <u>Annika Oehri, Alexandre Binninger, Aviv</u> Segall





- Total of 5 mandatory + 1 optional assignments
  - Each to be completed in 2-3 weeks' time
- Deliverables: code + live demo (sometimes a minireport)
  - Graded on all mandatory assignments
  - Instructions given per assignment
- Submit until 10:00 on the day of the due date
- Late submissions not accepted, strict policy.



# Rules of the Game - live demo

- We tell you what to show, in-person
- During the exercise session slot
- 3-4 minutes per person, schedule announce beforehand
- We might ask you to change the mesh or parameters





- One mini-exam
  - multiple-choice questions
  - 60 minutes
  - Wed 28.05.2025, 10:00, during the lecture time





- Grading = Exercises (80%) + mini-exam (20%), 8 credits
  - Assignments are weighed differently

	ex1	ex2	ex3	ex4	ex5	ex6	mini-exam
Weight/Points	10	16	Optional	16	16	22	20

- Zero points for copied code or report
- Be fair, be honest and have fun
  - Do not make your code public, even after the semester ends!







- We will run a plagiarism check on all the assignments
  - Including ones from previous years
  - Plagiarism could lead to expulsion from the course







# Asking questions

- Through Github issues (on the template repo)
  - Do not use e-mails to directly ask questions to TAs
  - Please check if your question has already been asked before posting
  - Feel free to answer questions by other students!
  - Don't wait until the last minute with problems



# repo) stions to TAs ady been asked

# r students! **problems**



# Asking questions

- Q&A sessions during TA slots.
  - Presence not mandatory, content not necessary for assignments.
  - Use it if you need to show your code...
  - ... but remember: you are expected to understand your algorithms and debug your code yourself.





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# Asking questions

Any emergencies or personal concerns:
 e-mail at <u>igl.lectures@inf.ethz.ch</u>





# Assignment Overview

ex	Title	Main TA	Start	End
1	Mesh "Hello World"	Aviv Segall	21.02.2025	07.03.2025
2	Surface reconstruction	Alexandre Binninger	07.03.2025	28.03.2025
3	Discrete differential geometry	Alexandre Binninger	21.03.2025	N/A
4	Mesh parameterization	Annika Oehri	28.03.2025	02.05.2025
5	Shape deformation	Annika Oehri	02.05.2025	23.05.2025
6	Skinning & deformation	Aviv Segall	16.05.2025	13.06.2025





# Ex1 Mesh "Hello World!"



Set up the environment and get familiar with libigl



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# **Ex2 Surface Reconstruction**



Input 3D points

3D meshes reconstructed from input using different parameters



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# Ex3 discrete differential geometry



Curvature



### Smoothing



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# Ex4 Mesh parameterization



Mapping 2D textures to 3D surfaces



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# Ex5 Shape deformation



Implement a UI to perform shape deformation



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# Ex6 Skeletal animation









- We use Git classroom, see instructions: <u>https://github.com/</u> eth-igl/GP2005-Assignments
- Reports should be placed in Readme.md of each assignment and nicely typeset.
- You can use STL & Eigen but no non-standard dependencies.





## Assignments on Git

# Add your name and email address

### Student data

Name: 'Your real name' Legi-Nr: 'Your legi number'

Email: 'Your email address'

- Commit and push your code frequently
- Regularly check the main repository for updates and new instruction:
  - https://github.com/eth-igl/GP2025-Assignments
  - Update the new assignments manually if 'git pull base main' doesn't work for you.





- /!\ Compile in **Debug** mode to get more info on errors, compile in **Release** mode for better speed
- This can make a huge difference for interactive problems that should run in real-time (e.g., assignment 5)



# ore info on better speed interactive e (e.g.,





- We will check your code in detail if we have doubts about your results.
- Remove unnecessary print statements from your final submission. They slow things down.
  - We will subtract points for unnecessary slow demos.
- Use command line/GUI parameters (e.g. to change a mesh). Don't hardcode & recompile to change it!







- We offer support on Windows and MacOS if you have problems compiling, especially at the beginning.
- For other OS, it should work fine as well, but it is your responsibility.
  - Exception: WSL likely won't work







### libigl - A simple C++ geometry processing library 🧪





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# Read and display a mesh



bunny.obj







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# Perform simple neighborhood calculations





vertex-to-face

vertex-to-vertex



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## Connected components



















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- A C++ template library for linear algebra: matrices, vectors, numerical solvers, and related algorithms
  - <u>http://eigen.tuxfamily.org/</u>
- Header-only library
  - No compilation required!
- Tutorials:
  - http://eigen.tuxfamily.org/dox/group\_\_TutorialMatrixClass.html
  - http://eigen.tuxfamily.org/dox/group\_QuickRefPage.html
  - IMPORTANT: <a href="https://eigen.tuxfamily.org/dox/TopicPitfalls.html">https://eigen.tuxfamily.org/dox/TopicPitfalls.html</a>

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## Mesh Representation with Eigen

## An Eigen matrix

Eigen::Matrix< type, #rows, #cols>

$$V = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 0 \end{pmatrix} \qquad F = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 3 & 2 \end{pmatrix} \qquad 0 \qquad 1$$

Eigen::Matrix<double, Eigen::Dynamic, 3> V; Eigen::Matrix<int, Eigen::Dynamic, 3> F;

Have a look at: <u>http://eigen.tuxfamily.org/dox/GettingStarted.html</u> 











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## Eigen common pitfalls



```
Eigen::Matrix3d a;
a << ...
a = a.transpose();  // WRONG!
a = a + a.transpose();  // WRONG!
a = a * a; // That's actually fine
```



Solution:

```
Eigen::Matrix3d a;
a << ...
a.transposeInPlace();
a = (a + a.transpose()).eval();
```







## Eigen common pitfalls

Aliasing issues:

Eigen::Matrix3d a; a << ... a = a.transpose(); a = a + a.transpose( a = a \* a; // That's



## a \* a; // That's Run your code in debug!

Solution:

```
Eigen::Matrix3d a;
a << ...
a.transposeInPlace()
a = (a + a.transpose
```

Runtime assertions will save your day





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V.rows(); v++) {
vg = avg\_neighbors(v);
V.row(v) + 0.8 \* avg;

V.rows(); v++) {
.vg = avg\_neighbors(v);
V.row(v) +
avg.transpose();



- Open source C++ library for geometry processing
  - Minimal dependencies
  - Header-only
  - No complex data types
- Dependencies: Eigen, GLFW, imgui, ...
  - All included as submodules in libigl
- Tutorials that explain the main functionality
  - Compilation instructions: see assignment sheet
- Header files contain documentation for functions





- Display mesh
- Very basic UI
- More options in code

# Demo tutorial 106





- Custom callbacks for keyboard/mouse interactions supported See tutorial 103 Events
- Also supported: Face/Vertex Colors, Overlays (points/lines)
  - See tutorials 104\_Colors, 105\_Overlays
- See https://libigl.github.io/tutorial/





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- Compiles a single main.cpp that runs the viewer
  - Assignment tasks are to be implemented as key interactions
  - '1' '2' : neighborhood relations
  - '3' '5': shading
  - '6': connected components
  - '7': subdivision





- Use Visual Studio Code
- Useful extensions:
  - cmake tools: UI for cmake
  - clangd: better syntax analysis





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Microsoft		
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LLVM		<b>6</b> 2023





### CMake Tools

### Choose kit (use clang on Mac, not gcc)





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### CMake Tools

- Choose kit (use clang on Mac, not gcc)
- Configure



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## • CMake Tools

- Choose kit (use clang on Mac, not gcc)
- Configure
- Build

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## • CMake Tools

- Choose kit (use clang on Mac, **not gcc**)
- Configure
- Build
- Run/Debug

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### CMake Tools - suggested setup

Separate folder for Release/Debug (avoid recompiling everything when switching configuration)









# Thank you!



February 24, 2023

